

Lecture 9
Systems of linear diff. equations

$$\left\{ \begin{array}{l} y'_1 = a_{11}(x) \cdot y_1 + a_{12}(x) \cdot y_2 + \dots + a_{1n}(x) \cdot y_n + b_1(x) \\ y'_2 = a_{21}(x) \cdot y_1 + \dots + a_{2n}(x) \cdot y_n + b_2(x) \\ \vdots \\ y'_n = a_{n1}(x) \cdot y_1 + \dots + a_{nn}(x) \cdot y_n + b_n(x) \end{array} \right.$$

$$Y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}, \quad A = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \\ a_{n1} & \dots & a_{nn} \end{pmatrix}, \quad B = \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$$

$$\Rightarrow \boxed{Y' = A \cdot Y + B} \quad \text{the vectorial form of the system.}$$

$$A \in C(I, M_{nn}(\mathbb{R}))$$

$$B \in C(I, \mathbb{R}^n)$$

(1) $\dot{Y} - A \cdot Y = B$ the nonhomogeneous system.

(2) $\dot{Y} - A \cdot Y = 0$ the homogeneous system

Theorem 1. The IVP:

$$\begin{cases} \dot{Y} - A \cdot Y = B \\ Y(a) = r, \quad r \in \mathbb{R}^n \end{cases}$$

has an unique solution.

The homogeneous case

(2) $\dot{Y} - AY = 0$

$$S_0 = \left\{ Y \in C^1(I, \mathbb{R}^n) \mid \dot{Y} - AY = 0 \right\}$$

$$L: C^1(I, \mathbb{R}^n) \rightarrow C(I, \mathbb{R}^n)$$

$$Y \mapsto L(Y)$$

$$L(Y) = \dot{Y} - A \cdot Y$$

the operator L is a linear operator.

L is linear $\Leftrightarrow \mathbf{y}^1, \mathbf{y}^2 \in C^1(I, \mathbb{R}^n)$, $\alpha, \beta \in \mathbb{R}$ then

$$L(\alpha \cdot \mathbf{y}^1 + \beta \cdot \mathbf{y}^2) = \alpha \cdot L(\mathbf{y}^1) + \beta L(\mathbf{y}^2)$$

(2) $\Leftrightarrow L(\mathbf{y}) = \emptyset$

$$\boxed{S_0 = \ker L}$$

Theorem 2. S_0 is a linear subspace of the linear space $C^1(I, \mathbb{R}^n)$ with $\dim S_0 = n$.

Proof. $S_0 = \ker L$ $\left. \begin{array}{l} L \text{ is a linear operator} \\ \end{array} \right\} \Rightarrow S_0 \text{ is a linear subspace of } C^1(I, \mathbb{R}^n).$

Let us denote by $\mathbf{Y}(\cdot; \alpha, \nu)$ the solution of the IVP:

$$\begin{cases} L(\mathbf{Y}) = 0 \\ \mathbf{Y}(\alpha) = \nu \end{cases} \quad I = [\alpha, b]$$

$$\varphi: \mathbb{R}^n \rightarrow S_0$$

$$\nu \mapsto \mathbf{Y}(\cdot; \alpha, \nu)$$

from Th. 1 $\Rightarrow \varphi$ is bijective

φ is a linear isomorphism of linear spaces.

$$\Leftrightarrow \varphi(\lambda_1 r^1 + \lambda_2 r^2) \stackrel{?}{=} \lambda_1 \varphi(r^1) + \lambda_2 \varphi(r^2) \quad \text{if } \lambda_1, \lambda_2 \in \mathbb{R} \\ r^1, r^2 \in \mathbb{R}^n$$

$\varphi(\lambda_1 r^1 + \lambda_2 r^2)$ is the sol. $\mathcal{Y}(\cdot; a, \lambda_1 r^1 + \lambda_2 r^2)$

$$\begin{cases} L(\mathcal{Y}) = 0 \\ \mathcal{Y}(a) = \lambda_1 r^1 + \lambda_2 r^2 \end{cases} \quad (3)$$

$\varphi(r^1)$ is the sol. $\mathcal{Y}(\cdot; a, r^1)$

$$\begin{cases} L(\mathcal{Y}) = 0 \\ \mathcal{Y}(a) = r^1 \end{cases}$$

$\varphi(r^2)$ is the sol. $\mathcal{Y}(\cdot; a, r^2)$

$$\begin{cases} L(\mathcal{Y}) = 0 \\ \mathcal{Y}(a) = r^2 \end{cases}$$

$$V = \lambda_1 \cdot \mathcal{Y}(\cdot; a, r^1) + \lambda_2 \cdot \mathcal{Y}(\cdot; a, r^2) \in S_0 \quad \left. \begin{array}{l} \\ \end{array} \right\} \Rightarrow V \text{ is a solution} \\ \left. \begin{array}{l} \\ \\ \end{array} \right\} \text{of the IVP (3)}$$
$$V(a) = \lambda_1 r^1 + \lambda_2 r^2$$
$$\stackrel{\text{Th.1}}{\Rightarrow} V = \mathcal{Y}(\cdot; a, \lambda_1 r^1 + \lambda_2 r^2) \rightarrow \varphi(\lambda_1 r^1 + \lambda_2 r^2) = \lambda_1 \varphi(r^1) + \lambda_2 \varphi(r^2)$$

$$\Rightarrow \boxed{\dim S_0 = \dim \ker L = n} \Rightarrow \{ Y^1, Y^2, \dots, Y^n \} \subset S_0$$

a basis in S_0

$\forall Y \in S_0 \quad \exists c_1, \dots, c_n \in \mathbb{R}$ such that:

$$Y = c_1 Y^1 + c_2 Y^2 + \dots + c_n Y^n$$

we denote by $U = (Y^1 \ Y^2 \ \dots \ Y^n) \Rightarrow$

$$\Rightarrow \boxed{Y = U \cdot \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix}}$$

$\{Y^1, Y^2, \dots, Y^n\}$ is a basis in $S_0 \Leftrightarrow \{Y^1, Y^2, \dots, Y^n\}$ is called a fundamental system of solutions.

the matrix $U = (Y^1 \ Y^2 \ \dots \ Y^n)$ is called the fundamental matrix of solutions.

To solve the system (2) means to find a fundamental matrix of solutions.

$\{\underline{y}^1, \dots, \underline{y}^n\} \subset S_0$ is a basis in $S_0 \iff \{\underline{y}^1, \dots, \underline{y}^n\}$ is linearly independent system of functions.

$\underline{y}^1, \dots, \underline{y}^n$ are linearly dependent \iff if $\exists (c_1, \dots, c_n) \neq 0$ such that $c_1 \underline{y}^1 + \dots + c_n \underline{y}^n = 0$

$\underline{y}^1, \dots, \underline{y}^n$ are linearly independent \iff

$$\iff c_1 \underline{y}^1 + \dots + c_n \underline{y}^n = 0 \Rightarrow c_1 = c_2 = \dots = c_n = 0$$

$$W(x; \underline{y}^1, \dots, \underline{y}^n) = \begin{vmatrix} y_1^1 & y_1^2 & \dots & y_1^n \\ y_2^1 & y_2^2 & \dots & y_2^n \\ \vdots & \vdots & & \vdots \\ y_n^1 & y_n^2 & \dots & y_n^n \end{vmatrix} \text{ the wronskian of } \underline{y}^1, \dots, \underline{y}^n$$

$$\underline{y}^1 = \begin{pmatrix} y_1^1 \\ \vdots \\ y_m^1 \end{pmatrix}, \dots, \underline{y}^n = \begin{pmatrix} y_1^n \\ \vdots \\ y_m^n \end{pmatrix}$$

Theorem 3:

a) If $y^1, \dots, y^n \in C([a, b], \mathbb{R}^n)$ are linearly dependent \Rightarrow

$$\Rightarrow W(\cdot; y^1, y^2, \dots, y^n) \equiv 0$$

b) If $y^1, \dots, y^n \in S_0 = \ker L$ are linearly independent \Rightarrow

$$\Rightarrow W(x; y^1, \dots, y^n) \neq 0, \forall x \in [a, b].$$

Proof. a) y^1, \dots, y^n are linearly dependent \Rightarrow one function is a linear combination of other $n-1$ functions

\Rightarrow one column of W is a linear combination of other $n-1$ columns of W

$$\Rightarrow W(x; y^1, \dots, y^n) = 0, \forall x \in [a, b].$$

b) Suppose $\exists x_0 \in [a, b]$ such that $W(x_0; y^1, \dots, y^n) = 0$.

we consider the system :

$$\underbrace{\begin{pmatrix} y^1(x_0) & y^2(x_0) & \dots & y^n(x_0) \end{pmatrix}}_A \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_m \end{pmatrix} = 0. \quad (4)$$

$$\det A = W(x_0; y^1, \dots, y^n) = 0 \Rightarrow$$

$$\Rightarrow \exists \begin{pmatrix} \tilde{x}_1 \\ \tilde{x}_2 \\ \vdots \\ \tilde{x}_m \end{pmatrix} \neq \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix} \text{ solution of the system (4).}$$

we construct the function

$$\tilde{Y} = (Y^1 \dots Y^n) \begin{pmatrix} \tilde{x}_1 \\ \tilde{x}_2 \\ \vdots \\ \tilde{x}_m \end{pmatrix} \Rightarrow \tilde{Y} \in S_0 \Rightarrow L(\tilde{Y}) = 0$$

$$\tilde{Y}(x_0) = (Y^1(x_0) \dots Y^n(x_0)) \begin{pmatrix} \tilde{x}_1 \\ \vdots \\ \tilde{x}_m \end{pmatrix} = 0$$

\tilde{Y} is a solution of the IVP

$$\begin{cases} L(Y) = 0 \\ Y(x_0) = 0 \end{cases} \quad \text{but } Y \equiv 0 \text{ is also a sol of this IVP}$$

$$\Rightarrow \tilde{Y} \equiv 0 \Rightarrow \tilde{x}_1 Y^1 + \dots + \tilde{x}_m Y^m = 0$$

with $\begin{pmatrix} \tilde{x}_1 \\ \vdots \\ \tilde{x}_m \end{pmatrix} \neq \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}$

$\Rightarrow Y^1, \dots, Y^m$ are linearly dependent
 \Rightarrow contradiction

∴ So we have the following possibilities:

- if $\underline{Y}^1, \dots, \underline{Y}^n \in S_0$ are linearly dependent \Rightarrow

$$\Rightarrow W(x; \underline{Y}^1, \dots, \underline{Y}^n) = 0, \forall x \in [a, b]$$

- if $\underline{Y}^1, \dots, \underline{Y}^n \in S_0$ are linearly independent \Rightarrow

$$\Rightarrow W(x; \underline{Y}^1, \dots, \underline{Y}^n) \neq 0, \forall x \in [a, b].$$

Theorem 4. (The wronskian criterion)

$\{\underline{Y}^1, \dots, \underline{Y}^n\}$ is a fundamental system of solutions

for (2) $\Leftrightarrow \exists x_0 \in [a, b]$ such that $W(x_0; \underline{Y}^1, \dots, \underline{Y}^n) \neq 0$.

The nonhomogeneous case

$$(1) \quad Y' - AY = B. \quad A \in C([a,b], M_m(\mathbb{R})) \\ B \in C([a,b], \mathbb{R}^n)$$

$$(1) \Leftrightarrow L(Y) = B.$$

$S = \{ Y \in C^1([a,b], \mathbb{R}^n) \mid L(Y) = B \}$ the solution set.

$$S = S_0 + \{ Y^P \} = \ker L + \{ Y^P \}$$

where Y^P is a particular solution of (1).

if. U is a fundamental matrix of (2). then the general solution of (1)

$$\boxed{Y = U \cdot \begin{pmatrix} c_1 \\ \vdots \\ c_n \end{pmatrix} + Y^P, \quad c_1, \dots, c_n \in \mathbb{R}}$$

$$\boxed{Y = Y^0 + Y^P} \quad \text{where } Y^0 \text{ is the gen. sol. of (2)} \\ Y^P \text{ is a partic. sol. of (1).}$$

The variation of the constants method

$$Y^P = ?$$

We try to find $Y^P(x) = U(x) \cdot \begin{pmatrix} \varphi_1(x) \\ \vdots \\ \varphi_m(x) \end{pmatrix}$

$$(Y^P)' - A \cdot Y^P = B.$$

$$\left(1. U \cdot \begin{pmatrix} \varphi_1 \\ \vdots \\ \varphi_m \end{pmatrix} \right)' = U' \cdot \begin{pmatrix} \varphi_1 \\ \vdots \\ \varphi_m \end{pmatrix} + U \cdot \begin{pmatrix} \varphi_1' \\ \vdots \\ \varphi_m' \end{pmatrix}$$
$$\left(2. U' - A \cdot U = 0 \right)$$

$$\Rightarrow \left(U \cdot \begin{pmatrix} \varphi_1 \\ \vdots \\ \varphi_m \end{pmatrix} \right)' - A \cdot \left(U \cdot \begin{pmatrix} \varphi_1 \\ \vdots \\ \varphi_m \end{pmatrix} \right) = B.$$

$$\underbrace{U' \cdot \begin{pmatrix} \varphi_1 \\ \vdots \\ \varphi_m \end{pmatrix}}_{=0} + U \cdot \begin{pmatrix} \varphi_1' \\ \vdots \\ \varphi_m' \end{pmatrix} - \underbrace{A \cdot U \cdot \begin{pmatrix} \varphi_1 \\ \vdots \\ \varphi_m \end{pmatrix}}_{=0} = B$$

$$\underbrace{(U' - A \cdot U)}_{=0} \cdot \begin{pmatrix} \varphi_1 \\ \vdots \\ \varphi_m \end{pmatrix} + U \cdot \begin{pmatrix} \varphi_1' \\ \vdots \\ \varphi_m' \end{pmatrix} = B \Rightarrow$$

$$U^{-1} \cdot \left| U \cdot \begin{pmatrix} \varphi_1' \\ \vdots \\ \varphi_m' \end{pmatrix} = B \right. \Rightarrow$$

$$\det U(x) = \text{W}(x; \underline{\gamma}^1, \dots, \underline{\gamma}^m) \neq 0.$$

U is a fundam. matrix
of solutions

$$\Rightarrow \begin{pmatrix} \varphi_1' \\ \vdots \\ \varphi_m' \end{pmatrix} = U^{-1} \cdot B$$

$$\begin{pmatrix} \varphi_1'(x) \\ \vdots \\ \varphi_m'(x) \end{pmatrix} = U^{-1}(x) \cdot B(x)$$

$$\Rightarrow \begin{pmatrix} \varphi_1'(x) \\ \vdots \\ \varphi_m'(x) \end{pmatrix} = \int_{x_0}^x U^{-1}(s) \cdot B(s) ds$$

$$\underline{\gamma}^P = U \cdot \begin{pmatrix} \varphi_1 \\ \vdots \\ \varphi_m \end{pmatrix} \Rightarrow \boxed{\underline{\gamma}^P(x) = U(x) \cdot \int_{x_0}^x U^{-1}(s) \cdot B(s) ds}$$

The general sol. of (1):

$$\underline{\gamma} = \underline{\gamma}^0 + \underline{\gamma}^P \Rightarrow$$

$$\underline{Y}(x) = U(x) \cdot \begin{pmatrix} c_1 \\ \vdots \\ c_m \end{pmatrix} + U(x) \cdot \int_{x_0}^x U^{-1}(s) \cdot B(s) ds$$

$x_0 \in [a, b]$

Remarks

1) $\begin{cases} \underline{Y}' - A\underline{Y} = B \\ \underline{Y}(x_0) = V \end{cases}, V \in \mathbb{R}^m$

$$\underline{Y}(x_0) = V \Rightarrow U(x_0) \cdot \begin{pmatrix} c_1 \\ \vdots \\ c_m \end{pmatrix} = V \Rightarrow \begin{pmatrix} c_1 \\ \vdots \\ c_m \end{pmatrix} = U^{-1}(x_0) \cdot V$$

\Rightarrow the solution of IVP is

$$\underline{Y}(x) = U(x) \cdot U^{-1}(x_0) \cdot V + U(x) \cdot \int_{x_0}^x U^{-1}(s) \cdot B(s) ds.$$

2) $n=1 \quad y' - p \cdot y = q \quad p, q \in C([a, b], \mathbb{R})$

$$U(x) = e^{\int_{x_0}^x p(s) ds}$$

$$U^{-1}(x) = e^{-\int_{x_0}^x p(s) ds}$$

$$y(x) = c \cdot e^{\int_{x_0}^x p(s) ds} + e^{\int_{x_0}^x p(s) ds} \cdot \left(\int_{x_0}^x \left(e^{-\int_{x_0}^s p(t) dt} \cdot g(s) \right) ds \right)$$